

Jet Propulsion Laboratory California Institute of Technology

Low-order Wavefront Sensing Architecture and Results Summary

Brian Kern

Jet Propulsion Laboratory California Institute of Technology

Pasadena, CA 91109

August 26 – 27, 2024

Copyright 2024 California Institute of Technology. Government sponsorship acknowledged

NASA GODDARD SPACE FLIGHT CENTER • JET PROPULSION LABORATORY •
 L3HARRIS TECHNOLOGIES • BALL AEROSPACE • TELEDYNE • NASA KENNEDY SPACE CENTER •
 SPACE TELESCOPE SCIENCE INSTITUTE • INFRARED PROCESSING AND ANALYSIS CENTER •
 EUROPEAN SPACE AGENCY • JAPAN AEROSPACE EXPLORATION AGENCY •
 • CENTRE NATIONAL d'ÉTUDES SPATIALES • MAX PLANCK INSTITUTE FOR ASTRONOMY •



- Optical context for LOWFSC
- Estimator construction
- Tip-tilt nonlinearity
- Performance requirements verified by test
- Performance requirements verified by analysis



Contributors to design and analysis (not including hardware and software implementation):

Outline

David Arndt Eric Cady Mark Colavita Brandon Dube Nanaz Fathpour Clem Gaidon Katie Heydorff Milan Mandic Zahid Rahman Joon Seo Fang Shi Joel Shields Alfredo Valverde

CGI LOWFSC hardware and context





1. LOWFSC stabilizes incoming wavefront

- LOWFSC does not reduce CGI entrance pupil WFE
- LOWFSC feedback is continuous and real-time (millisec latencies, high flux)
- LOWFSC by itself does not enhance contrast
- LOWFSC enables HOWFSC to perform fine control that produces deep contrast
 - HOWFSC uses ground-in-the-loop, HOWFSC is set-and-forget
- LOWFSC enables long observations without losing deep contrast

- 2. LOWFSC enables star acquisition
- Roman slews leave observatory within ~ few arcsec of desired pointing
 - tolerance for centration on FPM is ~ mas
- CGI refines pointing to be within capture range of LoS loop and closes loop

August 26-27, 2024 CGI Test Results Info Session

Jet Propulsion Laboratory

California Institute of Technology



LOWFSC Zernike mode morphologies

50×50 pixel LOCam pupil images (intensities) from model



at FPM:

HLC FPM dielectric thickness pattern, $0 - 1.5 \ \mu m$ thick

FPM

source

image



PSF FWHM

no quantitative consideration for LOWFSC in design of dielectric pattern; not a simple Zernike spot!

shown in LOCam orientation reference LOWFSC image Zernike x -0.10 0.05 θ (input pupil=1) 0.00 Zernike y Z_3 Z_8 Z_2 Z_4 Z_{5} Z_7 Z_9 Z_{11} Z_6 Z_{10} 0.15-0.00 -0.15[intensity/rad] FSM FCM DM1 LOCam calibration delta-intensity images pupil image HLC input wavefront is very non-flat (PV ~ λ) FPM does not have simple morphology CGI does not use "traditional" Zernike Wavefront Sensor ٠ capability to measure wavefront phase directly

August 26-27, 2024 CGI Test Results Info Session imperfect analogy with ZWS

4



HLC LOWFSC morphologies



nonquantitiative morphological match between model and measured is similar, but with fine-scale differences

these model results have not been updated with the observed CVS + NKT illumination spectrum

- morphologies evolve significantly with wavelength
 - 510 640 nm
- CVS + NKT is FF redder than stellar me spectrum





Jet Propulsion Laboratory California Institute of Technology

construction of an estimator (1)



- LOWFSC estimator is a matrix-vector multiply operation that acts on every LOCam frame (at 1 kHz)
- the estimator determines coefficients to spatial modes, using a linear least-squares fit, to best describe the pixel-by-pixel values in the new LOCam frame
- in addition to 10 Zernike coefficients (Z2 Z11), include coefficients for 4 other modes:
 - uniform camera bias (+1 for every pixel) 1.
 - dark-subtracted LOWFSC reference image (variable to account for flux calibration errors or flux changes, and establish zero-points) 2.
 - LOCam-x shear of dark-subtracted LOWFSC reference (camera stability separate from coronagraphic optical train) 3.
 - LOCam-y shear of dark-subtracted LOWFSC reference 4.
 - additional terms do not correspond to controls, but separately solving for them avoids misinterpreting benign errors / disturbances as control inputs affecting the coronagraphic optical train



August 26-27, 2024 CGI Test Results Info Session

all but 1 of estimator inputs are empirically measured



construction of an estimator (2)



- Each 50×50 pixel array in the decomposition is vectorized into a 2500-element pixel vector, and all these vectors are stacked into a 2500×17 matrix
 - 3 "unused" columns are all zeros
 - this matrix is a Jacobian, with elements $\partial I_j / \partial c_i$ the change in intensity at pixel j per change in coefficient i

 $Zmm = [\partial I_j / \partial c_0 \partial I_j / \partial c_1 \dots \partial I_j / \partial c_{16}]$

 c_0 is uniform bias, $c_1...c_{10}$ are Z2-Z11 coefficients, c_{11} is flux, c_{12} - c_{13} are x- and y-shear

The Moore-Penrose pseudoinverse of Zmm is denoted P

 $P = Zmm^{\dagger}$

- P is a 17x2500 matrix
- The per-frame dark subtraction is calibrated by calculating a vector Q = -P • (LOWFSC reference image before dark subtraction)
- For every LOCam frame A (vectorized into 2500 pixels), in real-time, a vector of coefficients is determined by

c = PA + Q

• c is a linear least-squares fit of intensity changes w.r.t. the LOWFSC reference image, with the changes decomposed into the empirical modes the estimator was trained to



tip-tilt nonlinearity



- Tip-tilt estimation (Z2-Z3) is sufficiently linear for feedback to LoS control
 - Tip-tilt residuals < 1 mas rms / axis when LoS loop is closed
 - nonlinearity of Z2-Z3 estimates
 is < 10% over +/- 10 mas
- Acquisition requires reliable LOWFSC capture over 80 mas radius
 - Z2, Z3 nonlinearities significant with zero-crossings and sign errors in that range



tip-tilt nonlinearity is significant for star > 10 mas off-center





performance requirements verified by test



- Top-level LOWFSC performance requirements verified by test in TVAC:
 - Cutoff frequency for tip-tilt rejection
 - Cutoff frequency for focus control rejection
 - Cutoff frequency for Z5-Z11 ("Zernike loop") rejection
 - LOWFSC capture range (80 mas radius, last step of acquisition)



LoS control (tip-tilt)

LOWFSC Estimator Tilt Sensing

Disturbance on

23:50

CTRL off



jitter mirror outside CGI introduced pre-determined disturbance profiles



Disturbance Rejection - close to perfect match with design:







23:55

Requirement	СВЕ		Margin (%)
	Х	У	
1.0 mas	0.45 mas	0.31 mas	55

Disturbance on

00:10

CTRL on

00:05

LOS

00:00

closed

Z3 (100ms avg)

40 nm

20 nm

0 nm -20 nm

-40 nm



Z4 (focus) rejection



Metric	Requirem ent	Z4 Design	Z4 Estimate
Disturbance rejection bandwidth (Hz)	0.0016	0.0013	0.0013
Gain margin (dB)	> 6	14	13.8
Phase margin(deg)	> 30	75	69
Delay (sec)	20	20	20

ROMAN CORONAGRAPH





August 26-27, 2024 CGI Test Results Info Session

.



Metric	Requirement	Z5-Z11 Design	Z5-Z11 Estimate
Disturbance rejection bandwidth (Hz)	0.0016	0.0016	0.0014
Gain margin (dB)	> 6	9.5	9.5
Phase margin (deg)	> 30	46	43
Delay (sec)	< 20	14.33	15.5 median

Z5-Z11 (Zernike Loop) rejection









All loops closed, with dark hole measurements



- A variety of data were taken with all loops running, while EXCam was observing a "good dark hole" solution
 - These would be ideal for determining "truth" of LOWFSC stabilization of contrast
- The analysis of these data is complicated by challenges with EXCam flux normalization
 - These tests were determined to be out of scope for requirements verification
 - Activities funded by overguide testing
- Data taken in flight will be the relevant test



LOWFSC capture range (pointing)



LOWFSC capture (tip-tilt) is complicated by nonlinearity of estimator (FPM phase away from onaxis)

Jet Propulsion Laboratory

California Institute of Technology



path taken during LOWFSC capture (model)



Tests involved positioning the star at different points on the FPM, and closing the LoS loop.

The most interesting test results show "slow" capture at FPM locations where Z2-Z3 estimates are weak, but eventual capture

capture tests were successful



4.8 mas / row or col; 80 mas = 17 rows or cols

August 26-27, 2024 CGI Test Results Info Session



Spectroscopy and Wide FoV configuration







performance requirements verified by analysis



- Crosstalk and pointing repeatability are dominated by chromatic effects
 - LOWFSC is "trained" on a blue reference star
 - reference star spectral types O-B
 - calibration data from a blue reference star are used on red target star
 - target star spectral types F-G-K
 - across 128 nm-wide band, ratio of short-to-long wavelength spectral density changes by ~ 2× for change in spectral type
- for the same PSF centration and WFE, LOWFSC image morphology is different on red star vs blue star
 - changes both in zero-point and in differential mode morphology
- for CVS + NKT spectral input, only short- and long-wavelength cutoff are controlled
 - Test-As-You-Fly exception that we cannot test the operational concepts with flight-like stellar spectra



510-536 nm



536-562 nm





562-588 nm



588-614 nm



614-640 nm





August 26-27, 2024 CGI Test Results Info Session

model validation not yet performed



Summary



- LOWFSC system meets performance requirements on disturbance rejection, LOWFSC capture range
 - Several L4 LOWFSC requirements were verified by analysis
 - Loops did not diverge under "flight-like" operational conditions
- More detailed stability experiments were not conducted in TVAC due to uncertainties associated with TVAC environment, CVS and light source variability and lack of detailed monitoring
 - Out of scope of requirements verification
 - Some model verification data collected but not yet quantitatively compared