

Jet Propulsion Laboratory California Institute of Technology

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Low-order Wavefront Sensing Architecture and Results Summary

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• Optical context for LOWFSC

- **Estimator construction**
- Tip-tilt nonlinearity
- Performance requirements verified by test
- Performance requirements verified by analysis

Contributors to design and analysis (not including hardware and software implementation):

Outline

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CGI LOWFSC hardware and context

1. LOWFSC stabilizes incoming wavefront

- LOWFSC does not reduce CGI entrance pupil WFE
- LOWFSC feedback is continuous and real-time (millisec latencies, high flux)
- LOWFSC by itself does not enhance contrast
- LOWFSC enables HOWFSC to perform fine control that produces deep contrast
	- HOWFSC uses ground-in-the-loop, HOWFSC is set-and-forget
- LOWFSC enables long observations without losing deep contrast
- 2. LOWFSC enables star acquisition
- Roman slews leave observatory within \sim few arcsec of desired pointing
	- tolerance for centration on FPM is \sim mas
- CGI refines pointing to be within capture range of LoS loop and closes loop

LOWFSC Zernike mode morphologies

50×50 pixel LOCam pupil images (intensities) from model

at FPM:

HLC FPM dielectric thickness pattern, $0 - 1.5$ µm thick

FPM

source image

PSF FWHM

no quantitative consideration for LOWFSC in design of dielectric pattern; not a simple Zernike spot!

shown in LOCam orientation reference LOWFSC image Zernike x -0.10 I θ 0.05 (input pupil=1) 0.00 Zernike y Z_2 Z_3 Z_4 Z_5 Z_6 Z_7 Z_8 Z_9 Z_{10} Z_{11} 0.15 -0.00 -0.15 [intensity/rad] FSM FCM DM1 LOCam calibration delta-intensity images pupil image HLC input wavefront is very non-flat (PV $\sim \lambda$) • FPM does not have simple morphology • CGI does not use "traditional" Zernike Wavefront Sensor capability to measure wavefront phase directly

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imperfect analogy with ZWS

HLC LOWFSC morphologies

nonquantitiative morphological match between model and measured is similar, but with fine-scale differences

these model results have not been updated with the observed CVS + NKT illumination spectrum

- morphologies evolve significantly with wavelength
	- $510 640$ nm
- CVS + NKT is redder than stellar spectrum

construction of an estimator (1)

- LOWFSC estimator is a matrix-vector multiply operation that acts on every LOCam frame (at 1 kHz)
- the estimator determines coefficients to spatial modes, using a linear least-squares fit, to best describe the pixel-by-pixel values in the new LOCam frame
- in addition to 10 Zernike coefficients $(Z2 Z11)$, include coefficients for 4 other modes:
	- 1. uniform camera bias (+1 for every pixel)
	- 2. dark-subtracted LOWFSC reference image (variable to account for flux calibration errors or flux changes, and establish zero-points)
	- 3. LOCam-x shear of dark-subtracted LOWFSC reference (camera stability separate from coronagraphic optical train)
	- 4. LOCam-y shear of dark-subtracted LOWFSC reference
	- additional terms do not correspond to controls, but separately solving for them avoids misinterpreting benign errors / disturbances as control inputs affecting the coronagraphic optical train

construction of an estimator (2)

- Each 50×50 pixel array in the decomposition is vectorized into a 2500-element pixel vector, and all these vectors are stacked into a 2500×17 matrix
	- 3 "unused" columns are all zeros
	- this matrix is a Jacobian, with elements ∂I_j/∂c_i the change in intensity at pixel j per change in coefficient i

Zmm = [∂I_j/∂c₀ ∂I_j/∂c₁ ... ∂I_j/∂c₁₆]

 c_0 is uniform bias, $c_1...c_{10}$ are Z2-Z11 coefficients, c_{11} is flux, c_{12} - c_{13} are x- and y-shear

• The Moore-Penrose pseudoinverse of Zmm is denoted P

 $P = Zmm^{\dagger}$

- P is a 17x2500 matrix
- The per-frame dark subtraction is calibrated by calculating a vector Q = -P • (LOWFSC reference image before dark subtraction)
- For every LOCam frame A (vectorized into 2500 pixels), in real-time, a vector of coefficients is determined by

 $c = P A + Q$

• c is a linear least-squares fit of intensity changes w.r.t. the LOWFSC reference image, with the changes decomposed into the empirical modes the estimator was trained to

tip-tilt nonlinearity

- Tip-tilt estimation (Z2-Z3) is sufficiently linear for feedback to LoS control
	- Tip-tilt residuals < 1 mas rms / axis when LoS loop is closed
	- nonlinearity of Z2-Z3 estimates is < 10% over +/- 10 mas
- Acquisition requires reliable LOWFSC capture over 80 mas radius
	- Z2, Z3 nonlinearities significant with zero-crossings and sign errors in that range

August 26-27, 2024 CGI Test Resultable **tip-tilt nonlinearity is significant for star > 10 mas off-center and ^{4.8} mas / row or col; 80 mas = 17 rows or co**

performance requirements verified by test

- Top-level LOWFSC performance requirements verified by test in TVAC:
	- Cutoff frequency for tip-tilt rejection
	- Cutoff frequency for focus control rejection
	- Cutoff frequency for Z5-Z11 ("Zernike loop") rejection
	- LOWFSC capture range (80 mas radius, last step of acquisition)

LoS control (tip-tilt)

jitter mirror outside CGI introduced pre-determined disturbance profiles

Disturbance Rejection – close to perfect match with design:

Sample disturbance rejection movie of LOCAM images (loop closed at 1.6 second mark)

Z4 (focus) rejection

Z5-Z11 (Zernike Loop) rejection

All loops closed, with dark hole measurements

- A variety of data were taken with all loops running, while EXCam was observing a "good dark hole" solution
	- These would be ideal for determining "truth" of LOWFSC stabilization of contrast
- The analysis of these data is complicated by challenges with EXCam flux normalization
	- These tests were determined to be out of scope for requirements verification
		- Activities funded by overguide testing
- Data taken in flight will be the relevant test

LOWFSC capture (tip-tilt) is complicated by nonlinearity of estimator (FPM phase away from onaxis)

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path taken during LOWFSC capture (model)

Tests involved positioning the star at different points on the FPM, and closing the LoS loop.

The most interesting test results show "slow" capture at FPM locations where Z2-Z3 estimates are weak, but eventual capture

capture tests were successful

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Spectroscopy and Wide FoV configuration

performance requirements verified by analysis

- Crosstalk and pointing repeatability are dominated by chromatic effects
	- LOWFSC is "trained" on a blue reference star
		- reference star spectral types O-B
	- calibration data from a blue reference star are used on red target star
		- target star spectral types F-G-K
	- across 128 nm-wide band, ratio of short-to-long wavelength spectral density changes by \sim 2× for change in spectral type
- for the same PSF centration and WFE, LOWFSC image morphology is different on red star vs blue star
	- changes both in zero-point and in differential mode morphology
- for CVS + NKT spectral input, only short- and long-wavelength cutoff are controlled
	- Test-As-You-Fly exception that we cannot test the operational concepts with flight-like stellar spectra

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Summary

- LOWFSC system meets performance requirements on disturbance rejection, LOWFSC capture range
	- Several L4 LOWFSC requirements were verified by analysis
	- Loops did not diverge under "flight-like" operational conditions
- More detailed stability experiments were not conducted in TVAC due to uncertainties associated with TVAC environment, CVS and light source variability and lack of detailed monitoring
	- Out of scope of requirements verification
	- Some model verification data collected but not yet quantitatively compared