

**Jet Propulsion Laboratory** California Institute of Technology

### **CGI High-Order Wavefront Sensing and Control (HOWFSC) Architecture and Results Summary**

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# HOWFSC architecture



### **What is HOWFSC?**





CGI high-order wavefront sensing and control (HOWFSC):

- measures electric fields at the science focal-plane
- uses that information, along with a model of the system, to adjust the DMs to minimize residual starlight in focal-plane regions of interest ("dark hole")

Necessary to meet our contrast requirements! Can't get dark enough with good alignment + good optics



### **Wavefront estimation (pairwise probing)**



For correction, we need to know the complex image-plane electric field  $(A(x, y)e^{i\phi(x, y)})$ from starlight.

What we actually have is the intensity  $(|A(x, y)|^2)$  added on top of intensities from other sources ("incoherent light", e.g. planets/disks/exozodi, stray light, ghosts and other unusable starlight) for a total intensity of  $|A(x, y)|^2 + I_{inc}(x, y)$ .



Solution: use a set of positive and negative *probes*—small DM settings in the pupil—to modulate the wavefront and take images. [Give'on, Kern, and Shaklan 2011]

- We use pairs to simplify the estimation of the probe amplitude.
- Get probe phase from optical model (not measured directly)
- Minimum of five images (2 pairs + unprobed) for five independent variables
	- CGI uses seven images (3 pairs + unprobed) to avoid noise-induced ill-conditioning on 2x2 inversion, and to compensate for areas of low modulation

Get final  $I_{inc}(x, y)$  by subtracting  $|A(x, y)|^2$  from an unprobed image.



### **Wavefront control (electric-field conjugation)**



Basic EFC approach (Give'on et al. 2007): assume the field near the current position can be modeled as:

$$
E_1(x, y) \approx E_0(x, y) + \sum_n a_n J_n(x, y)
$$

for DM actuator settings *a*, and solve for *a* to minimize

$$
\left| E_0(x, y) + \sum_n a_n J_n(x, y) \right| \Big|_2
$$

In practice we discretize to get

 $||E + Ia||_2$ 

and solve an *Ax = b* equation as solution to least-squares problem with standard linear-algebra tools.

CGI extensions to this:

- Use weightings  $(W_F)$  on pixels to remove dead pixels, emphasize regions
- Use weightings on actuators ( $W<sub>DM</sub>$ ) to capture dead or tied actuators
- *E* will include pixels from several different wavelengths to capture chromatic variation
- Add a regularization term (λ) to balance model (*J*) vs data (*E*)
	- "Control strategy" can change these weights and regularizations per iteration
	- Use regularization scheduling to "ratchet" to higher contrast (see Cady et al. 2017, Seo et al. 2017, Marx et al. 2017)

$$
A = W_{DM}^T J^T W_E^T W_E J W_{DM} + \lambda I
$$
  

$$
B = W_{DM}^T J^T W_E^T E_0
$$

Final CGI tweak: minimize intensity *relative to PSF peak* ("normalized" intensity) rather than just intensity to keep the PSF sharp (see Section 3.3 of Llop-Sayson et al. 2022)



### **HOWFSC optical model**



We use an optical model of CGI, simplified for HOWFSC relative to high-fidelity model from Integrated Modeling, to:

- calculate probe phases (wavefront estimation)
- calculate Jacobians (wavefront correction)
- calculate contrast estimates for the next iteration (operator monitoring, camera-settings calculation)



Dedicated data collection activities and ground software (GSW) tools used to build the optical model from a combination of measured data and design specifications.

The primary reason HOWFSC will slow or stop at moderate contrasts is model mismatch!



### **Ground-in-the-loop (GITL)**



Until late 2019, HOWFSC was planned to be done entirely onboard in FSW

- Separate dedicated copy of CGI processing board in hardware (SSP)
	- Active work to accelerate Jacobian and model calculation via attached RTG4 FPGA and integrate calculation periods into ops, as computation timing did not close otherwise
	- Also used board for calibrations (e.g. phase retrieval)
- Dedicated solid-state recorder (SSR) for Jacobian storage (tens of GB)

October 2019: Mission PDR raised red flags about FSW schedule risk, particularly for HOWFSC, along with mass/power

- Moved HOWFSC to GITL approach
	- On board: collect EXCAM data, process to "thin" Level 2b, combine and crop (for data volume)
	- On ground: run wavefront estimation and control on full set of images to select new DM setting
- Moved nearly all calibration, alignment, etc. functionality to ground as well, and descoped SSP and SSR

#### CGI benefits:

- Reduced mass/power/FSW lines of code/complexity and simplified V&V
	- A very real chance the CGI instrument would not have been able to be completed on time if this didn't occur
- Simpler and more effective implementation in GSW
	- Disjoint skillsets: FSW implementation required algorithm SMEs writing reference implementation with tests, and FSW engineers porting code and tests, to get around lack of personnel with HOWFSC *and* FSW experience
	- Timing/computation/storage issues disappear when modern COTS hardware can be thrown at the problem



### **Ground-in-the-loop (GITL) overview: flight**







### **GITL overview: II&T TVAC**









# HOWFSC results summary



### **Performance summary**









### **HOWFSC results: Band 1 narrow-field-of-view (NFOV)**





- Control run over 3-9 λ/D; TTR5 region is 6-9 λ/D. (Third run shown)
- Coronagraph architecture: Hybrid Lyot Coronagraph
- Contrast limited by time available and incoherent light leak setting contrast floor (addressed by additional baffle post-TVAC)



### **HOWFSC results: Band 1 wide-field-of-view (WFOV)**





- Control run over 6-20 λ/D; TTR5 region is 6-9 λ/D (One run only, shown above)
- Coronagraph architecture: Shaped Pupil Coronagraph
- Contrast limited by time available ("target of opportunity")



### **Open issues and lessons learned from TVAC**



Stellar centration was a limiting factor on NFOV runs 1 and 2

- Model mismatch: control model centration not consistent with tilt from LOWFSC
- Root cause was incomplete tip-tilt removal in front-end phase retrieval (low points skewed fit)
- Iterations built up a decenter in the line-of-sight offsets
- Started from scratch for run 3 (shown in movie)
	- Updated software tools to keep phase retrieval from repointing PSF
	- Measured the centration with a dedicated data collection activity and included in the model, and added this activity to operations plan going forward

During nulling in runs 1-2, found that we needed to swap DM probes to probes centered at different places on the DM before

- Never seen this in technology maturation testing or model-based evaluations
- Root cause still under investigation (including if it was linked to the mismatch above)

Nice-to-have: increased confidence in the coherent/incoherent split, as incoherent requirements are looser

Will require a delve into wavefront estimation theory



## **Summary**



#### Key takeaways

- Achieved > TTR5-level performance with two independent coronagraph architectures covering 3-9 and 6-20 λ/D between them with a 360° dark hole on both
	- Ultimate CGI contrast floor not known—performance limited by available time rather than any identified instrument systematic
- HOWFSC and calibration GSW all worked together the first time in TVAC
	- Benefit of using high-heritage/high-TRL algorithms + extensive unit-level and functional testing in advance
- Tested in best test-as-you-fly configuration (onboard collection, CTC+SSC software on "ground" running HOWFSC)
	- End-to-end information transfer for GITL will be tested at the observatory level, with the entire ground system in the loop





## BACKUP



### **Best tech maturation contrast: HLC in Milestone 9**





Best HLC performance during Milestone 9 (2017) by Joon Seo

Roughly, this probably represents the achievably raw-contrast floor for HLC observations