

Jet Propulsion Laboratory California Institute of Technology

CGI High-Order Wavefront Sensing and Control (HOWFSC) Architecture and Results Summary

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HOWFSC architecture



What is HOWFSC?





CGI high-order wavefront sensing and control (HOWFSC):

- measures electric fields at the science focal-plane
- uses that information, along with a model of the system, to adjust the DMs to minimize residual starlight in focal-plane regions of interest ("dark hole")

Necessary to meet our contrast requirements! Can't get dark enough with good alignment + good optics



Wavefront estimation (pairwise probing)



For correction, we need to know the complex image-plane electric field $(A(x, y)e^{i\phi(x, y)})$ from starlight.

• What we actually have is the intensity $(|A(x, y)|^2)$ added on top of intensities from other sources ("incoherent light", e.g. planets/disks/exozodi, stray light, ghosts and other unusable starlight) for a total intensity of $|A(x, y)|^2 + I_{inc}(x, y)$.



Solution: use a set of positive and negative *probes*—small DM settings in the pupil—to modulate the wavefront and take images. [Give'on, Kern, and Shaklan 2011]

- We use pairs to simplify the estimation of the probe amplitude.
- Get probe phase from optical model (not measured directly)
- Minimum of five images (2 pairs + unprobed) for five independent variables
 - CGI uses seven images (3 pairs + unprobed) to avoid noise-induced ill-conditioning on 2x2 inversion, and to compensate for areas of low modulation

Get final $I_{inc}(x, y)$ by subtracting $|A(x, y)|^2$ from an unprobed image.



Wavefront control (electric-field conjugation)



Basic EFC approach (Give'on et al. 2007): assume the field near the current position can be modeled as:

$$E_1(x,y) \approx E_0(x,y) + \sum_n a_n J_n(x,y)$$

for DM actuator settings a, and solve for a to minimize

$$\left\|E_0(x,y) + \sum_n a_n J_n(x,y)\right\|_2$$

In practice we discretize to get

 $||E + Ja||_2$

and solve an Ax = b equation as solution to least-squares problem with standard linear-algebra tools.

CGI extensions to this:

- Use weightings (W_E) on pixels to remove dead pixels, emphasize regions
- Use weightings on actuators (W_{DM}) to capture dead or tied actuators
- E will include pixels from several different wavelengths to capture chromatic variation
- Add a regularization term (λ) to balance model (J) vs data (E)
 - "Control strategy" can change these weights and regularizations per iteration
 - Use regularization scheduling to "ratchet" to higher contrast (see Cady et al. 2017, Seo et al. 2017, Marx et al. 2017)

$$A = W_{DM}^{T} J^{T} W_{E}^{T} W_{E} J W_{DM} + \lambda I$$
$$B = W_{DM}^{T} J^{T} W_{E}^{T} E_{0}$$

Final CGI tweak: minimize intensity *relative to PSF peak* ("normalized" intensity) rather than just intensity to keep the PSF sharp (see Section 3.3 of Llop-Sayson et al. 2022)

August 26-27, 2024 CGI Test Results Info Session



HOWFSC optical model



We use an optical model of CGI, simplified for HOWFSC relative to high-fidelity model from Integrated Modeling, to:

- calculate probe phases (wavefront estimation)
- calculate Jacobians (wavefront correction)
- calculate contrast estimates for the next iteration (operator monitoring, camera-settings calculation)



Dedicated data collection activities and ground software (GSW) tools used to build the optical model from a combination of measured data and design specifications.

The primary reason HOWFSC will slow or stop at moderate contrasts is model mismatch!



Ground-in-the-loop (GITL)



Until late 2019, HOWFSC was planned to be done entirely onboard in FSW

- Separate dedicated copy of CGI processing board in hardware (SSP)
 - Active work to accelerate Jacobian and model calculation via attached RTG4 FPGA and integrate calculation periods into ops, as computation timing did not close otherwise
 - Also used board for calibrations (e.g. phase retrieval)
- Dedicated solid-state recorder (SSR) for Jacobian storage (tens of GB)

October 2019: Mission PDR raised red flags about FSW schedule risk, particularly for HOWFSC, along with mass/power

- Moved HOWFSC to GITL approach
 - On board: collect EXCAM data, process to "thin" Level 2b, combine and crop (for data volume)
 - On ground: run wavefront estimation and control on full set of images to select new DM setting
- Moved nearly all calibration, alignment, etc. functionality to ground as well, and descoped SSP and SSR

CGI benefits:

- Reduced mass/power/FSW lines of code/complexity and simplified V&V
 - A very real chance the CGI instrument would not have been able to be completed on time if this didn't occur
- Simpler and more effective implementation in GSW
 - Disjoint skillsets: FSW implementation required algorithm SMEs writing reference implementation with tests, and FSW engineers
 porting code and tests, to get around lack of personnel with HOWFSC and FSW experience
 - Timing/computation/storage issues disappear when modern COTS hardware can be thrown at the problem



Ground-in-the-loop (GITL) overview: flight







GITL overview: II&T TVAC









HOWFSC results summary



Performance summary





L4 Raw Contrast Requirements	Requirement	NFOV/HLC 6-9 λ/D Data	WFOV/SPC 6-9 λ/D Data
Imaging with Narrow FoV Initial Static Coherent Raw Contrast, 6-9 λ/D , narrow FoV mode, filter band 1	≤ 5x10 ⁻⁸	0.98x10 ⁻⁸	1.42x10 ⁻⁸
Imaging with Narrow FoV Initial Static Incoherent Raw Contrast, 6-9 λ/D , narrow FoV mode, filter band 1	≤ 1x10 ⁻⁷	2.35x10 ⁻⁸	2.96x10 ⁻⁸



HOWFSC results: Band 1 narrow-field-of-view (NFOV)





- Control run over 3-9 λ /D; TTR5 region is 6-9 λ /D. (Third run shown)
- Coronagraph architecture: Hybrid Lyot Coronagraph
- Contrast limited by time available and incoherent light leak setting contrast floor (addressed by additional baffle post-TVAC)



HOWFSC results: Band 1 wide-field-of-view (WFOV)





- Control run over 6-20 λ /D; TTR5 region is 6-9 λ /D (One run only, shown above)
- Coronagraph architecture: Shaped Pupil Coronagraph
- Contrast limited by time available ("target of opportunity")



Open issues and lessons learned from TVAC



Stellar centration was a limiting factor on NFOV runs 1 and 2

- Model mismatch: control model centration not consistent with tilt from LOWFSC
- Root cause was incomplete tip-tilt removal in front-end phase retrieval (low points skewed fit)
- Iterations built up a decenter in the line-of-sight offsets
- Started from scratch for run 3 (shown in movie)
 - Updated software tools to keep phase retrieval from repointing PSF
 - Measured the centration with a dedicated data collection activity and included in the model, and added this activity to operations plan going forward

During nulling in runs 1-2, found that we needed to swap DM probes to probes centered at different places on the DM before

- Never seen this in technology maturation testing or model-based evaluations
- Root cause still under investigation (including if it was linked to the mismatch above)

Nice-to-have: increased confidence in the coherent/incoherent split, as incoherent requirements are looser

• Will require a delve into wavefront estimation theory



Summary



Key takeaways

- Achieved > TTR5-level performance with two independent coronagraph architectures covering 3-9 and 6-20 λ/D between them with a 360° dark hole on both
 - Ultimate CGI contrast floor not known—performance limited by available time rather than any identified instrument systematic
- HOWFSC and calibration GSW all worked together the first time in TVAC
 - Benefit of using high-heritage/high-TRL algorithms + extensive unit-level and functional testing in advance
- Tested in best test-as-you-fly configuration (onboard collection, CTC+SSC software on "ground" running HOWFSC)
 - End-to-end information transfer for GITL will be tested at the observatory level, with the entire ground system in the loop





BACKUP



Best tech maturation contrast: HLC in Milestone 9





Best HLC performance during Milestone 9 (2017) by Joon Seo

Roughly, this probably represents the achievably raw-contrast floor for HLC observations